## IN-CYLINDER FLOW CHARACTERIZATION USING VORTICITY BASED PARAMETERS

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#### ABSTRACT

The paper deals with intake swirling flow characterization in the cylinder of IC engine. The commonly used method based on the swirl resp. tumble number from angular momentum flux evaluation does not need to give the appropriate values in some cases. Typically, in the case of two intake ports, a counter-rotating swirl vortex pair is presented. However their summary angular momentum flux is zero a thus corresponding swirl number is zero too. In order to correctly quantify these cases, it is proposed to evaluate so called vorticity numbers, i.e. dimensionless numbers based on vorticity evaluation. Concrete results are evaluated from data obtained using 3-D CFD simulation in AVL FIRE code. Comparison of variously defined vorticity numbers with each other and with the vortex numbers is performed. A practical way of calculating the vorticity numbers was also suggested with regard to possible adverse effects of the velocity gradients at the cylinder wall.

**KEYWORDS: IN-CYLINDER FLOW, SWIRL NUMBER, TUMBLE NUMBER, VORTICITY** 

#### SHRNUTÍ

Článek se zabývá problematikou kvantifikace úrovně velkých vírových pohybů ve válci spalovacího motoru. Obvykle používaný způsob založený na vyhodnocení vírového čísla swirlu a tumblu z toku momentu hybnosti nemusí v některých případech dávat odpovídající hodnoty. Typicky v případě dvou sacích kanálů vzniká výrazná dvojice protiběžných vírů, která ale souhrnně má nulový moment hybnosti a tedy i vírové číslo. Aby bylo možné tyto případy správně kvantifikovat, je navrženo vyhodnocovat vířivostní čísla, tj. bezrozměrná čísla založená na vyhodnocení vířivosti. Konkrétní výsledky jsou dokumentovány na datech získaných pomocí 3-D CFD simulace v programu AVL FIRE. Je provedeno porovnání jednotlivých vířivostních čísel navzájem i s vírovými čísly. Byl navržen i praktický způsob výpočtu vířivostních čísel s ohledem na možné nepříznivé ovlivnění velkými rychlostními gradienty u stěny válce. **KLÍČOVÁ SLOVA: PROUDĚNÍ VE VÁLCI, VÍROVÉ ČÍSLO, VÍROVÉ ČÍSLO TEČNÉ ROTACE, VÍROVÉ ČÍSLO PŘÍČNÉ ROTACE, VÍŘIVOST** 

#### **1. INTRODUCTION**

Knowledge of gas motion during exchange phase of internal combustion engine (ICE) is very important for optimizing following engine cycle phases – compression and combustion. In-cylinder flow during gas exchange has a significant impact for improving engine combustion performance in terms of large-scale coherent structure formation and in-cylinder turbulence level. In-cylinder flow is very complicated dynamic process, but to make it possible to describe it by the available resources, it is necessary to make some simplifications.

The first simplification consists in the idea of two predominant shapes of the in-cylinder coherent flow structure to swirl and tumble motion – Figure 1. These basic flow structures play an important role due to their ability to maintain turbulence level during compression and enhance mixing of fuel and air. Determination of swirling motion under conditions of actual engine operation is very demanding and expensive. Experimentally it is feasible only with test engine with optical access by using optical velocity measurement method like LDA or PIV. Full numerical simulation of real in-cylinder flow is very difficult, expensive and time consuming.

Therefore, although in-cylinder flow is a very dynamic process, the second simplification – steady flow testing of cylinder head – is a widely used method in development of engines. Steady flow testing can be done experimentally using a steady flow test rig or by means of numerical simulation.

A non-dimensional parameters called Swirl, resp. Tumble Number are used for swirl or tumble level characterization. Unfortunately no standard testing methodology currently exists.





Angular momentum flux based definitions of swirl or tumble number are more commonly used. However in some cases their use may give obviously misleading results.

Therefore new non-dimensional parameters based on vorticity evaluation were proposed. Three different parameters are defined in the present article and their use is compared on two typical examples of in-cylinder flow. These examples also show that it is a very important how these parameters are eva

# PARAMETERS

In-cylinder swirling flow is most often character angular momentum of cylinder charge. During the stead of flow test, you can evaluate (or measure) the angular momentum flux in some cross section area in the engine cylinder:

$$\dot{\vec{B}} = \int_{A} (\vec{r} \times \varrho \vec{u}) \vec{u} \cdot dA \tag{1}$$

where:  $\varrho$  ... density,  $r^{2}$ ... position vector,  $u^{2}$ ... velocity vector, A ... cross section area.

Displacement of the cross section corresponds to the position of the measurement element during swirl or tumble measurement. In both cases, cross section is a circular area, perpendicular to the z-axis, D ... diameter = cylinder bore. For the honeycomb torque meter used for the swirl measurement, displacement is 1.75 D (D ... diameter = cylinder bore), for tumble measurement by means original CTU tumble meter [1], displacement is 0.6 D. Swirl is characterized by swirl- i.e. z-component of angular momentum flux  $\vec{B}$ :

$$\begin{aligned} \|\dot{g}_{\text{ted}} = \dot{B}_z \overset{\dot{B}}{=} \dot{B}_z \overset{$$

**2. ANGULAR MOMENTUM FLUX BASED**  $\dot{B}_{S} = \dot{B}_{z} F_{\underline{or}}^{A}$  further the station diagram is necessary to merge x and  $\chi_{2}$  (2) component of angular momentum flux  $\vec{B}$ :

$$\dot{B}_{T} = \sqrt{\dot{B}_{x}^{\dot{B}_{T}} + \dot{B}_{y}^{2}} \dot{B}_{x}^{2} + \dot{B}_{y}^{2}} X \varrho u_{z}^{2} dA$$
(3)
(4)4)

(505)

Angular more flux components  $\vec{B}_s$  and  $\vec{B}_T$  can be measured (4) (1) or evaluated from CFD simulations. In this case, integrals must be evaluated numerically as sums.

Supposing that the cylinder charge is a solid rotating body, we 
$$\dot{B}_{\rm carr}$$
 is  $\dot{B}_{\rm carr}$  in  $\dot{B}_{\rm carr}$  is  $\dot{B}$ 

$$\dot{B} = \dot{I}.\,\omega = \dot{m}r_I^2.\,\omega \tag{5(5)}$$

$$\omega_{S} = \frac{8 \overset{\vec{B}}{\textit{bb}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{bb}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{bb}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}{\textit{b}} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}}{= = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}{m} \overset{\vec{B}}}{= = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}}{m} \overset{\vec{B}}{=} = \frac{8 \overset{\vec{B}}}{m} \overset{\vec{B}}}{m} \overset{\vec{B}}$$

$$\dot{B}_{S} = \dot{B}_{z} - \int_{A} (u_{x} u_{y} - v_{z} u_{z}) \varrho u_{z} dA$$

(6)In-Cylinder Flow Charactering atten Using Yorticity Based Parameters  $\omega_T =$ PETR HATSCHBACH, OLDRICH VITEK, RATER / TICHÁNEK  $\dot{m}.D^2$ MECCA 01 2021 PAGE 22

u<sup>2</sup>dA

$$u_{z mean} \underbrace{u_{z mean}}_{p mean} \underbrace{u_{z me$$

$$\dot{B} = - \int$$

$$B_{T} = \sqrt{B_{x}^{N} + B_{y}^{2}} \dot{B}_{x}^{P} + \dot{B}_{y}^{2} \dot{B}_{x}^{2} + \dot{B}\dot{B}_{y}^{2} = \sqrt{\dot{B}_{x}^{2} + \dot{B}_{y}^{2}} \qquad SN_{r} = SN \cdot \frac{(1)}{Z} = \frac{2.D(4)}{\dot{m}^{2}} \dot{B}_{y}^{N} = T(4) \frac{D}{Z} = \frac{2.D(4)}{\dot{m}^{2}} \dot{B}_{y}^{N} = T(4) \frac{D}{Z} = \frac{2.D(4)}{\dot{m}^{2}} \dot{B}_{y}^{N} = T(4) \frac{D}{Z} = \frac{2.D(4)}{\dot{m}^{2}} \dot{B}_{y}^{N} = \frac{1}{2} \dot{M}_{y}^{N} = \frac{1$$

$$-TN_r = TN \cdot \frac{D}{Z} = \frac{2.D.\rho.\dot{B}_T}{\dot{R}_T}$$
(12)

where:  $I \dots$  moments of inertia flux,  $\omega \dots$  angular speed of solid  $B = I \dots = 2 m r r I \dots \omega = m r r I \dots \omega$  and  $m r I \dots \omega = m r I \dots \omega$  for  $m r I \dots r I \dots r$  and  $m r I \dots r I \dots r$ . circula Bcytindeword the algorithm of the statistic  $\omega = mr_1^2 \cdot \omega$ 

The angular speed of charge equivalent solid body rotation for swirl and tumble are:

$$= \frac{8.\dot{B}_{s}}{\dot{m}.D_{s}^{2}} = \frac{\omega_{s}}{8.\dot{B}_{s}} \frac{8.\dot{B}_{s}}{\dot{m}.D_{s}^{2}} \dot{B}_{s} \omega_{T} \cong \frac{\omega_{T}}{8.\dot{B}_{T}} \frac{B.\dot{B}_{T}}{\dot{m}.D_{s}^{2}} \dot{B}_{s} \dot{B}_{T}}{\dot{m}.D_{s}^{2}} \dot{B}_{s} \omega_{T} \cong \frac{B.\dot{B}_{T}}{\dot{m}.D_{s}^{2}} \dot{B}_{s} \dot{B}_{T}}{\dot{m}.D_{s}^{2}} \dot{B}_{s} \dot{B}_{T}} = \frac{8.\dot{B}_{T}}{ntefDed} \frac{\omega_{T}}{as} = \frac{1}{ntefDed} \frac{\omega_{T}}{as} = \frac{1}{ntef} \frac{\omega_{T}}{as} = \frac{1}{ntefDed} \frac{\omega_{T}}{as} = \frac{1}{ntefDed} \frac{\omega_{T}}{as} = \frac{1}{ntefDed} \frac{\omega_{T}}{as} = \frac{1}{ntef} \frac{\omega_{T}$$

$$\omega_{e} \stackrel{\underline{\omega}_{e}}{=} \frac{\underline{\omega}_{e} \stackrel{\underline{4}}{=} \stackrel{\underline{m}^{4} \cdot \underline{m}}{\omega_{e}} = \stackrel{\underline{4} \cdot \underline{m}}{\underline{\omega}_{e}} = \stackrel{\underline{4} \cdot \underline{m}}{\underline{\omega}_{e}} \stackrel{\underline{4} \cdot \underline{m}}{=} \stackrel{\underline{4} \cdot \underline{m}}{\underline{\omega}_{e}} \stackrel{\underline{4} \cdot \underline{m}}{=} \stackrel{\underline{4} \cdot \underline{m}}{\underline{\omega}_{e}} \stackrel{\underline{4} \cdot \underline{m}}{=} \stackrel{\underline{4} \cdot \underline{m}}{\underline{\omega}_{e}} \stackrel{\underline{6} \cdot \underline{1}}{=} \stackrel{\underline{2} \cdot \underline{2}}{\underline{2}} \stackrel{\underline{2} \cdot \underline{2}}{\text{ troke}} \stackrel{\underline{6} \cdot \underline{1}}{\underline{2}} \stackrel{\underline{2} \cdot \underline{2}}{\text{ troke}} \stackrel{\underline{6} \cdot \underline{1}}{\underline{2}} \stackrel{\underline{2} \cdot \underline{2}}{\underline{2}} \stackrel{\underline{2} \cdot \underline{2}}{\text{ troke}} \stackrel{\underline{6} \cdot \underline{1}}{\underline{2}} \stackrel{\underline{2} \cdot \underline{2}}{\underline{2}} \stackrel{\underline{2} \cdot \underline{2}} \stackrel{\underline{2} \cdot \underline{2}}{\underline{2}} \stackrel{\underline{2} \cdot \underline{2}} \stackrel{\underline{2} \cdot \underline{2}} \stackrel{\underline{2} \cdot \underline{2}}{\underline{2}} \stackrel{\underline{2} \cdot \underline{2}} \stackrel{\underline{2}$$

Rewriting the equations (6) and (8) the swirl and tumble number can be expressed as:

Non-dimensional parameters based on vorticity evaluation were defined in [5]. But those parameters are not very well named, because terms swirl and tumble ratios are often used =for non-dimensional weighted sum of the angular more htum introduced to the cylinder during the whole intake phase.

7) This paper, defines three dimensionless parameters based on three methods of mean vorticity evaluating:

AVG swirl vorticity number  $VN_{zAVG}$  computed from AVG vorticity  $\omega_{zAVG}$  calculated as area weighted mean z-component of vorticity:

$$V_{N_{z AVG}}^{(8)} = \frac{(8)_{z AVG}}{2. \omega_e}$$
 (8) (14)

$$\omega_{z AVG} = \frac{1}{A} \int_{AV_G} \left( \frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y} \right) dA \qquad (14)$$

$$VN_{z AVG} = \frac{1}{A} \int_{\omega_z} \left( \frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y} \right) dA \qquad (14)$$

$$VN_{z AVG} = \frac{1}{A} \int_{\omega_z} \left( \frac{\partial u_y}{\partial u_z} - \frac{\partial u_x}{\partial u_z} \right) dA$$

$$(9) \qquad (9) \qquad (9) \text{ABS vanishes vorticity number } VN_{zABJ} \text{ commuted from mean yort of } A$$

$$(9) \qquad (9) \qquad (9) \text{ABS vanishes vorticity number } VN_{zABJ} \text{ commuted absoluted value } z - \text{ common ent}$$

 $SN = \frac{1}{\omega_2} \frac{\mu_2}{\omega_1} \frac{\mu_2}{m_1} \frac{\mu_2}{m_2} \frac{\mu_2}{m_1} \frac{\mu_2}{m_2} \frac{\mu_2}{m_1} \frac{\mu_2}{m_2} \frac{\mu_2}{m_1} \frac$  $\frac{2}{2}$  of results between different engines) (YO) z ABS (in terms of design), a reduced swirl and tumble numbers are defined:  $D.Z.D.B_{TP}$ .  $TSN = SN = D = 2.D.D_{r}$ .  $SN_r = \omega SN \cdot Z = m^2 m^2_2$   $Z D = 2m^2$ .

 $\omega_{\omega_T}^{e} = \omega_T Z \rho_L B_L$ 

 $IN_r = IN \cdot Z \overline{D} = 2n$   $TN_r = DN \cdot Q = 2n$   $SN_r \equiv N_r = TN - Z = \frac{2}{2} \frac{n}{m^2}$ 

$$\binom{(10011)}{(11)}\omega_{z ABS} = \frac{1}{A} \int_{A} \left| \frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y} \right| dA$$
(15)  
$$\binom{(11)}{(12)} \binom{(11)}{(12)} (12) (12)$$
RMS swirl vorticity number  $VN_{z RMS}$  computed from measured

an (va)ticity  $\omega_{z RMS}$  calculated as area weighted root mean square (1(2))) value z-component of vorticity:

This definition2regueeBthe above-mentioned swirl and tumble  $TN_r$  numbers to the case of engine with 'square' design (bore equals) stroke). Reduced numbers do not have in terms of steady test a misleading dependence on the stroke Z.

#### 3. VORTICITY BASED PARAMETERS

2mD. p. B.

$$\begin{split} & \begin{array}{c} \partial u_y & \partial u_z \\ & \partial u_y & \partial u_z \\ \partial v_y & \partial u_z \\ & \begin{array}{c} \partial u_y & \partial u_z \\ \partial v_y & \partial v_z \\ \partial v_y & \partial v_z \\ \end{array} \\ & \begin{array}{c} \nabla \sigma & \sigma & \sigma \\ \partial v_y & \partial v_z \\ \partial v_y & \partial v_z \\ \end{array} \\ & \begin{array}{c} \nabla \sigma & \sigma & \sigma \\ \partial v_y & \partial v_z \\ \partial v_y & \partial v_z \\ \partial v_y & \partial v_z \\ \end{array} \\ & \begin{array}{c} \nabla \sigma & \sigma & \sigma \\ \partial v_y & \sigma & \sigma \\ \partial v_y & \sigma & \sigma \\ \end{array} \\ & \begin{array}{c} \nabla \sigma & \sigma & \sigma \\ \partial v_y & \sigma & \sigma \\ \partial v_y & \sigma & \sigma \\ \partial v_y & \sigma & \sigma \\ \end{array} \\ & \begin{array}{c} \nabla \sigma & \sigma & \sigma \\ \partial v_y & \sigma & \sigma \\ \partial v_y & \sigma & \sigma \\ \partial v_y & 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$$\omega_z = \frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y}$$

$$VN_{z RMS} = \frac{\omega_{z RMS}}{2.\,\omega_e} \tag{16}$$

$$\omega_{ZRMS} = \sqrt{\frac{1}{A} \int_{A} \left(\frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y}\right)^2} \, dA \tag{16}$$

ABS vorticity number can only be positive because it is calculated only from the absolute values of the partial vorticities. Each



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(161)3)

(15)

microscopic circulation contributes positively to the total sum. It is believed that this definition could be applicable to the overall quantification e.g. two counter-rotating vortex structures.

RMS-vorticity number will be qualitative similar to ABS vorticity number, but large vorticities will have a larger weight due to the calculation with quadrate of vorticity.

For swirling flow like a rotating rigid body, vorticity  $\omega_z$  in each point of z=const area and mean vorticity  $\omega_{zAVG}$  (and absoluted vorticity  $\omega_{zABS}$  too) have a same constant value equal to twice the angular velocity of rotating flow.

## 4. COMPUTED CASES AND METHOD OF EVALUATION

The results of simulations of steady flow test bench described in work [6] and other newly calculated results were used for comparison in the previous part described non-dimensional parameters. These are the results of intake port steady flow bench simulation of 4-valve SI engine (bore 76.5 mm). Two different cases were calculated: both intake valves are open (classical configuration, typical for SI engine, tumble dominated flow pattern) and single intake valve is open (unconventional, swirl dominated flow pattern). The valve lift was set from 1 to 9 mm.

Flow field was calculated by means of 3D CFD code AVL FIRE. PANS turbulence model, 4 boundary layers with 0.15 mm boundary layer thickness and unsteady simulation mode were used (up to time 0.160 s with step 0.00001 s). Boundary conditions correspond to steady flow test bench measurement setup – the most important one is the pressure difference between inlet and outlet was constant at the value of 5 kPa. More details about the calculation settings are described in [6].



FIGURE 2: Swirl and Tumble number – dependence on valve lift – the case of both intake valves being opened.

**OBRÁZEK** 2: Vírová čísla swirlu a tumblu – závislost na zdvihu ventilu – varianta se dvěma otevřenými sacími ventily.

Swirl and vorticity numbers were evaluated in planes placed 0.6 or 1.75 bore diameter respectively away from the cylinder head. These distances correspond to the location of the CTU tumble meter or honeycomb swirl meter. AVL FIRE command-line tool fire\_utils\_integrate was used to integrate CFD results over appropriate cell selection [7]. Subsequent evaluation was performed in the MS Excel spreadsheet.

#### **5. RESULTS AND DISCUSSION**

Evaluation of swirl and tumble number depending on valve lift is the usual method of large vortex movements' characterization. The case of both intake valve opened is shown in Figure 2. Tumble is dominant shape of the in-cylinder flow structure. The case of single intake valve opened is shown in Figure 3. Swirl is expected here as the main vortex shape. It is possible to make these conclusions:

- Swirl number in the case of both valve opened is practically zero. Only tumble number is evaluable.
- In the case of single valve opened it is possible to evaluate both swirl and tumble. Both swirl and tumble number curves have the similar quantity and trend.
- Relative level of large vortex structure in the case of both opened valves is always less than for single open valve case.
- Swirl number decreases slightly with the distance from the cylinder head.

Further evaluations will focus on the swirl in-cylinder motion. In Figure 4, 5, 6 and 7 are shown velocity and vorticity fields in distances 0.6D and 1.75D from cylinder head and for both cases of valve opening.



**FIGURE 3:** Swirl and Tumble number – dependence on valve lift – the case of single intake valve being opened.

**OBRÁZEK 3:** Vírová čísla swirlu a tumblu – závislost na zdvihu ventilu – varianta s jedním otevřeným sacím ventilem.



It can be seen that in the case of both valves opened – Figure 4 and 5, significant counter-rotating vortex pair is presented. However the swirl number SN, calculated from the angular momentum flux according to (9), is practically zero for all valve lift values. This is due to the fact that both swirl structures are approximately identical but counter-rotating, so that the angular momentum flux is virtually zero. Therefore, it is clear that the quantitative evaluation using the swirl number does not correspond to reality in these cases.

Because of their opposite orientation, both vortex will interact, slow down and gradually collapse into smaller vortex and chaotic turbulence in the intake stroke and early compression stroke. Just by comparing the velocity fields in distances 0.6D and 1.75D it is obvious that the vortex decay will be faster in the case of two counter-rotating vortices (both valve opened) than in case of single valve opened, when a single large vortex is created and filling the entire space of cross section. However, they certainly represent a significant part of the large vortex movements and should be considered.

A possible way to quantify the vortex level in these cases is to use appropriately defined vorticity numbers. The dependency of AVG, ABS and RMS vorticity number on valve lift is presented in Figure 8, 9 and 10 for cases of integration by formulas (14), (15) and (16) respectively. Vorticity numbers are evaluated in distances 0.6D and 1.75D and in circular area having 4 different diameters: 76.5 mm (the entire cylinder cross section), 76 mm, 74 mm and 72 mm. The case of both opened valvesi on the left, the case of single opened valve is on the right.

The first interesting conclusion follows from the chart of AVG vorticity number in Figure 8. AVG vorticity number is equal to zero when computed across the entire cross-section (D = 76.5 mm). This is in conformity with the Green's theorem, which describes a relationship between the macroscopic circulation around closed curve and the sum of all the microscopic circulation that is inside this curve. We can write integral in formula (14) as:

$$\int_{A} \left( \frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y} \right) dA = \oint_{\partial A} \vec{u} \cdot d\partial A = 0$$

and this integral is equal zero because of the zero fluid velocity  $u^{2}$  at the wall.

The second conclusion follows from Figure 8 left. For case of both intake ports opened the AVG vorticity number oscillates around zero. Therefore AVG vorticity number is not able to capture the effect of two counter-rotating vortices – like classical swirl number computed from angular momentum flux The third note is concerning the method of practical evaluation of the vorticity number. In the practical evaluation of the

vorticity numbers, it is necessary to deal with the problem related to the calculation of the respective component of the vorticity vector by the difference of the two partial derivations (13). In the area of large velocity gradients, the vorticity evaluation may be subject to large uncertainty, since actually two large numbers, calculated as a proportion of a large and a small number, are subtracted. This fact causes a further increase in the uncertainty of determining vorticity beyond the usual uncertainty in the numerical calculation of the derivative. Because large velocity gradients are usually only in the wall boundary layers with decreasing flow velocity, their real contribution to the quantification of large vortex structure (in terms of influence on angular momentum flux value) is small, insignificant. However, these large gradients have a big influence on the value of vorticity and vorticity numbers.

A possible solution is to exclude the area of the wall boundary layer in the evaluation. The gradual reduction of the influence of vorticity evaluated in the wall boundary layer to vorticity number was monitored – Figure 8, 9 and 10. Vorticity numbers evaluated from area without the wall boundary layer (diameter 76 mm and lower) are almost equal. Practical evaluation of the vorticity numbers is therefore appropriate to calculate in the area reduced by about 1 % of the cylinder diameter.

## **6. CONCLUSION**

The commonly used swirl and tumble number based on angular momentum flux evaluation fail to characterize the level of swirling movements in some cases – for example in case of counter-rotating swirl vortex pair added to dominant tumble motion. Proposed vorticity number can solved this problem because they characterize level of microscopic vortex structure on the scale corresponding to the evaluation mesh size.

However AVG vorticity number calculated as simple sum of appropriate vorticity component provides similar results like from angular momentum flux computed swirl number because it respects rotation direction too. ABS and RMS vorticity number responds correctly, as has been demonstrated by evaluating of two typical in-cylinder flow cases. It is probably more convenient to use the ABS vorticity number because the RMS vorticity number is calculated as the quadratic mean and thus overestimates larger vortices.

Vorticity number can be used as an auxiliary parameter to refine the characterization of intake swirling flow, for example as a correction factor to the standard swirl and tumble numbers. This is especially important in cases when there are two counter-rotating swirl vortices. The way to include vorticity number in the computational models will be the subject of further work.







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valves being opened

FIGURE 4: Velocity vector field and vorticity z-component (color scale) + swirl number and ABS

swirl vorticity number - distance 0.6D from cylinder head, dependence on valve lift - both intake

OBRÁZEK 4: Pole vektorů rychlosti a z-ové složky vířivosti + vírové číslo swirlu a ABS vířivostní číslo

swirlu – vzdálenost 0.6D od hlavy válce, závislost na zdvihu ventilu – otevřené oba sací ventily.

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**FIGURE 5:** Velocity vector field and vorticity z-component (color scale) + swirl number and ABS swirl vorticity number – distance 1.75D from cylinder head, dependence on valve lift – both intake valves being opened

**OBRÁZEK 5:** Pole vektorů rychlosti a z-ové složky vířivosti + vírové číslo swirlu a ABS vířivostní číslo swirlu – vzdálenost 1.75D od hlavy válce, závislost na zdvihu ventilu – otevřené oba sací ventily.







**FIGURE 6:** Velocity vector field and vorticity z-component (color scale) + swirl number and ABS swirl vorticity number – distance 0.6D from cylinder head, dependence on valve lift – single intake valve being opened.

**OBRÁZEK 6:** Pole vektorů rychlosti a z-ové složky vířivosti + vírové číslo swirlu a ABS vířivostní číslo swirlu – vzdálenost 0.6D od hlavy válce, závislost na zdvihu ventilu – otevřený jeden sací ventil.



**FIGURE 7:** Velocity vector field and vorticity z-component (color scale) + swirl number and ABS swirl vorticity number – distance 1.75D from cylinder head, dependence on valve lift – single intake valve being opened.

**OBRÁZEK 7:** Pole vektorů rychlosti a z-ové složky vířivosti + vírové číslo swirlu a ABS vířivostní číslo swirlu – vzdálenost 1.75D od hlavy válce, závislost na zdvihu ventilu – otevřený jeden sací ventil.





FIGURE 8: AVG swirl vorticity number – dependence on valve lift and max. diameter of evaluation area – the case with both open intake valves is on the left, the case with single open valve is on the right.

**OBRÁZEK 8:** AVG vířivostní číslo – závislost na zdvihu ventilu a max. průměru vyhodnocovací oblasti – varianta se dvěma otevřenými sacími ventily vlevo, s jedním otevřeným ventilem vpravo.



FIGURE 9: ABS swirl vorticity number – dependence on valve lift and max. diameter of evaluation area – the case with both open intake valves is on the left, the case with single open valve is on the right.

OBRÁZEK 9: ABS vířivostní číslo – závislost na zdvihu ventilu a max. průměru vyhodnocovací oblasti – varianta se dvěma otevřenými sacími ventily vlevo, s jedním otevřeným ventilem vpravo.



FIGURE 10: RMS swirl vorticity number – dependence on valve lift and max. diameter of evaluation area – the case with both open intake valves is on the left, the case with single open valve is on the right.

**OBRÁZEK 10:** RMS vířivostní číslo – závislost na zdvihu ventilu a max. průměru vyhodnocovací oblasti – varianta se dvěma otevřenými sacími ventily vlevo, s jedním otevřeným ventilem vpravo.



## **ACKNOWLEDGEMENTS**

This research has been realized using the support of Technological Agency, Czech Republic, programme Centres of Competence, project TE01020020: 'Josef Božek Competence Centre for Automotive Industry'.

This research has been realized using the support of EU Regional Development Fund in OP R&D for Innovations (OP VaVpI) and The Ministry of Education, Youth and Sports, Czech Republic, project CZ.1.05/2.1.00/03.0125: 'Acquisition of Technology for Vehicle Center of Sustainable Mobility'.

This research has been realized using the support of The Ministry of Education, Youth and Sports program NPU I (LO), project LO1311: 'Development of Vehicle Centre of Sustainable Mobility'. All the help has been gratefully appreciated.

#### LIST OF NOTATIONS AND ABBREVIATIONS

ation set)

AVG	average
ABS	absolute
RMS	root mean square
CTU	Czech Technical University in Prague
CFD	Computation Fluid Dynamics
ICE	Internal Combustion Engine
PANS	Partially Averaged Navier-Stokes (equ
LDA	Laser Doppler Anemometry
PIV	Particle Image Velocimetry

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